

Spedix Rex Betaflight Setup

- 1) TX setup: set model to multicopter, reverse yaw and roll channels, set roll, pitch, yaw, throttle endpoints to 147.
- 2) Plug into betaflight
- 3) Go to the CLI tab at the bottom
- 4) Paste below text into the CLI. Once pasted in, type 'save' to save the configuration. Once bound, the drone should now be fully configured.

On a DX6, GEAR channel = arm, AUX 1 = turtle mode pos 2, stability mode pos 1, acro mode pos 0

```
# version
# Betaflight / OMNIBUSF4SD (OBSD) 3.5.3 Nov 15 2018 / 00:20:01 (61d5abf00) MSP API: 1.40

board_name OMNIBUSF4SD
manufacturer_id

# name
name Modelflight

# resources

# mixer

# servo

# servo mix

# feature
feature -RX_PARALLEL_PWM
feature RX_SERIAL

# beeper

# beacon

# map
map TAER1234

# serial
serial 0 64 115200 57600 0 115200
serial 2 2048 115200 57600 0 115200

# led
```

color

mode_color

aux

aux 0 0 1 1700 2100 0 0

aux 1 2 0 1300 1700 0 0

aux 2 35 0 900 1300 0 0